

Distance, Displacement, Speed, Velocity and Acceleration

Suppose, relative to some coordinate system, that a particle is at position $\mathbf{r}(t_1)$ at time t_1 and at $\mathbf{r}(t_2)$ at time t_2 . Then the **average velocity** over the time interval $[t_1, t_2]$ is the rate of change of distance with respect to time which is **Average Velocity** $= \frac{\mathbf{r}(t_2) - \mathbf{r}(t_1)}{t_2 - t_1}$. To obtain the velocity at a point we just let $t_2 \rightarrow t_1$. The result is the derivative of $\mathbf{r}(t)$ with respect to time t . Thus the velocity at a point is $\mathbf{v} = \frac{d\mathbf{r}}{dt} = \left(\frac{dx}{dt}\right)\mathbf{i} + \left(\frac{dy}{dt}\right)\mathbf{j} + \left(\frac{dz}{dt}\right)\mathbf{k}$. i.e., when differentiating a vector, you differentiate it component wise. Similarly, the acceleration is the rate of change of velocity with time, i.e.,

$$\mathbf{a} = \frac{d\mathbf{v}}{dt} = \left(\frac{dv_x}{dt}\right)\mathbf{i} + \left(\frac{dv_y}{dt}\right)\mathbf{j} + \left(\frac{dv_z}{dt}\right)\mathbf{k}.$$

Bringing these results together we have

Position vector $\mathbf{r} = (x\mathbf{i} + y\mathbf{j} + z\mathbf{k}) \quad \text{m}$

Velocity vector $\mathbf{v} = \frac{d\mathbf{r}}{dt} = (v_x\mathbf{i} + v_y\mathbf{j} + v_z\mathbf{k}) = \left(\left(\frac{dx}{dt}\right)\mathbf{i} + \left(\frac{dy}{dt}\right)\mathbf{j} + \left(\frac{dz}{dt}\right)\mathbf{k}\right) \quad \text{m/s}$

Acceleration vector $\mathbf{a} = \frac{d\mathbf{v}}{dt} = (a_x\mathbf{i} + a_y\mathbf{j} + a_z\mathbf{k}) = \left(\left(\frac{dv_x}{dt}\right)\mathbf{i} + \left(\frac{dv_y}{dt}\right)\mathbf{j} + \left(\frac{dv_z}{dt}\right)\mathbf{k}\right) \quad \text{m/s}^2$

NB. Notice the basic units for position, velocity and acceleration in SI units. Also note that the dot notation can be used to indicate differentiation with respect to time, i.e., $\mathbf{v} = \dot{\mathbf{r}}, \mathbf{a} = \dot{\mathbf{v}} = \ddot{\mathbf{r}}$.

Example:- If the position vector of a particle at time t is $\mathbf{r}(t) = (t^2\mathbf{i} + 4t^3\mathbf{j} + (1 - \sin t)\mathbf{k})$, determine its velocity and acceleration at time t .

Here
$$\mathbf{v} = \frac{d\mathbf{r}}{dt} = \left(\frac{d}{dt}(t^2)\right)\mathbf{i} + \left(\frac{d}{dt}(4t^3)\right)\mathbf{j} + \left(\frac{d}{dt}(1 - \sin t)\right)\mathbf{k}$$
$$= 2t\mathbf{i} + 12t^2\mathbf{j} - \cos t\mathbf{k}$$

Also
$$\mathbf{a} = \left(\frac{d}{dt}(2t)\right)\mathbf{i} + \left(\frac{d}{dt}(12t^2)\right)\mathbf{j} - \left(\frac{d}{dt}\cos t\right)\mathbf{k}$$
$$= 2\mathbf{i} + 24t\mathbf{j} + \sin t\mathbf{k}$$

Example:- If the acceleration of a particle at time t is $\mathbf{a} = 2\mathbf{i} + 6\mathbf{j} + 9\mathbf{k}$, determine expressions for the velocity and position at time t .

Since $\mathbf{a} = \frac{d\mathbf{v}}{dt}$ then $\mathbf{v} = \int \mathbf{a} dt + \mathbf{C}$, where $\mathbf{C} = (C_x, C_y, C_z)$ is a vector constant of integration. Hence

$$\mathbf{v} = (\int 2dt)\mathbf{i} + (\int 6dt)\mathbf{j} + (\int 9dt)\mathbf{k} + \mathbf{C} = 2t\mathbf{i} + 6t\mathbf{j} + 9t\mathbf{k} + \mathbf{C}$$

Integrating again gives

$$\begin{aligned} \mathbf{r} &= (\int 2t dt)\mathbf{i} + (\int 6t dt)\mathbf{j} + (\int 9t dt)\mathbf{k} + \int \mathbf{C} dt \\ &= t^2\mathbf{i} + 3t^2\mathbf{j} + \frac{9}{2}t^2\mathbf{k} + \mathbf{C}t + \mathbf{B} \end{aligned}$$

where $\mathbf{B} = (B_x, B_y, B_z)$, is a vector constant of integration. As usual \mathbf{C} and \mathbf{B} can be determined when boundary conditions are given.

Note The distance of a particle from the origin is denoted as $|\mathbf{r}| = \sqrt{x^2 + y^2 + z^2}$

The speed of a particle is $v = |\mathbf{v}| = \sqrt{v_x^2 + v_y^2 + v_z^2}$, both are **positive scalar quantities**.

Velocity – time plot for 1 dimensional motion.

Suppose we were given the velocity-time plot shown below. Describe its features and determine the total distance travelled. We note the following:-

1. For the first 50 s the particle is travelling with constant acceleration since the plot is linear over this range. The acceleration is the rate of change of velocity and so the acceleration is

$$\begin{aligned} a &= \frac{\text{Change in vel}}{\text{change in time}} \\ &= \frac{20-0}{50} = 0.4ms^{-2} \end{aligned}$$

2. The velocity is constant for the next 35s and so the acceleration is 0 here.
3. The velocity declines to zero over the next 40s and so there is a retardation of $a = \frac{0-20}{40} = -0.5ms^{-2}$. This is also true for the last 10s.
4. Lastly, we note that the area under the velocity time curve is

$$\int_{t_0}^{t_1} v dt = \int_{t_0}^{t_1} \frac{dr}{dt} dt = \int_{t_0}^{t_1} dr = r(t_1) - r(t_0) = \text{Displacement}$$

Distance travelled in the first 125s, whilst the velocity is positive, is

$$\frac{50 \times 20}{2} + 35 \times 20 + \frac{20 \times 40}{2} = 1600m$$

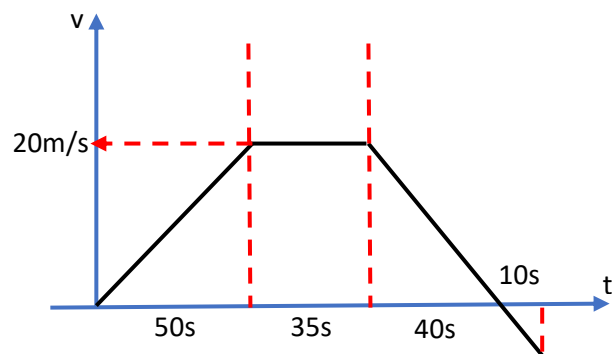
In the last 10s the velocity is negative, and equal to $-0.5 \times 10 = -5 ms^{-1}$ after 135s, and so it is travelling backwards to the origin from 125s. Distance travelled here is $\frac{10 \times 5}{2} = 25m$.

In summary

Displacement from the origin = $1600 - 25 = 1575m$

Distance travelled = $1600 + 25 = 1625m$

NB a curved section of the curve implies there is a time dependent acceleration.



Displacement-time plot associated with the above velocity-time plot

1. In the first 50s the velocity is proportional to time and is zero when $t = 0$. Thus $r = \int \frac{20t}{50} dt = 0.2t^2$. This is a quadratic, with a minimum at $t=0$ and rising to 500m when $t = 50$ s.
2. The velocity is constant(20m/s) for $50 < t < 85$. Therefore $r = 20(t - 50) + 500$ over this range. Thus, when $t = 85$, $r = 20 \times 35 + 500 = 1200m$.
3. For $85 < t < 135$, $v = -0.5(t - 85) + 20 = -0.5t + 62.5$ and so by integrating

$$r = -\frac{t^2}{4} + 62.5t + C. \text{ Now } r = 1200 \text{ when } t = 85, \text{ hence } C = -2306.25.$$

This distance is maximised when $v = 0$, i.e., when $t = 125$ s, the maximum value being 1600m.

The shape of this displacement time plot is shown below.

